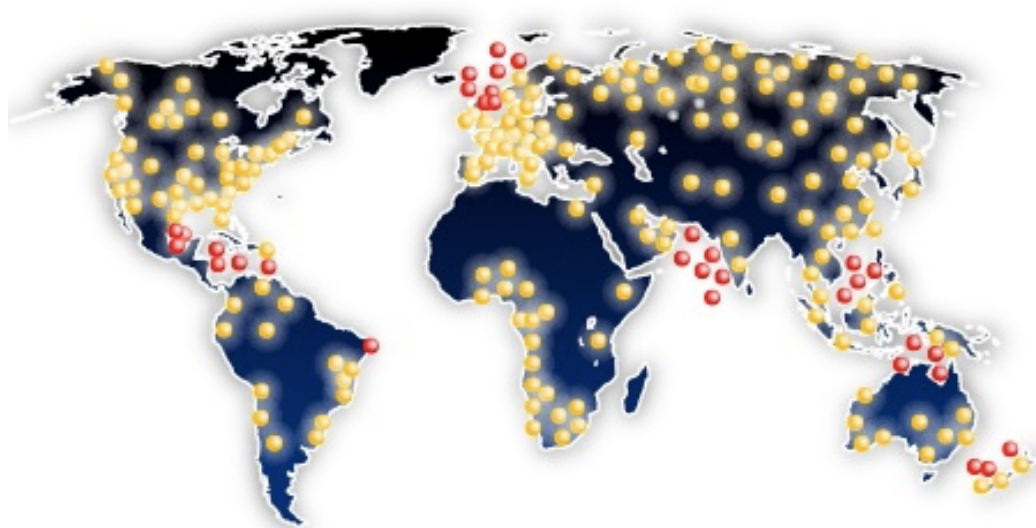


Efficient Holistic Control over Industrial Wireless Sensor-Actuator Networks

Yehan Ma, Chenyang Lu
Cyber-Physical Systems Laboratory

Industrial IoT for Industrial Internet



Offshore

Onshore

Courtesy: Emerson Process Management

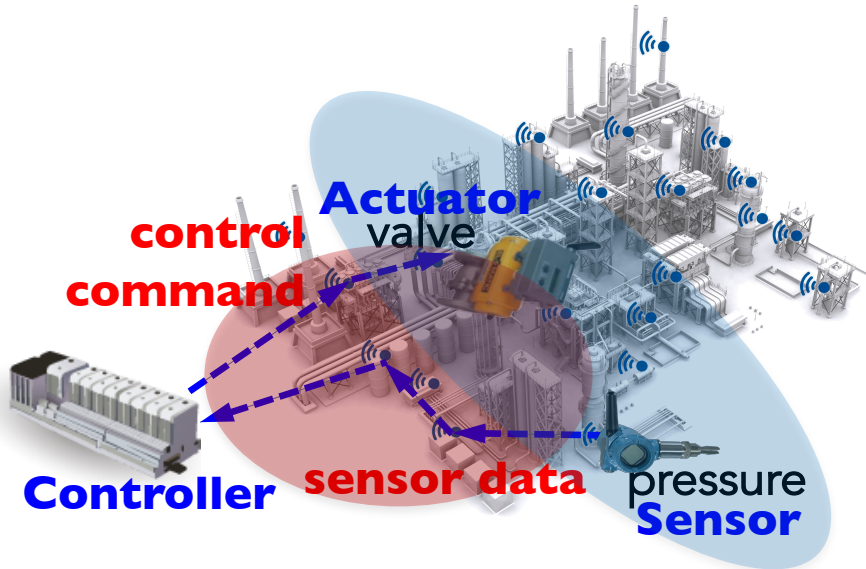
- 12.9+ billion hours operating experience
- 41,040+ wireless field networks

[Emerson]

- \$123 billion by 2021

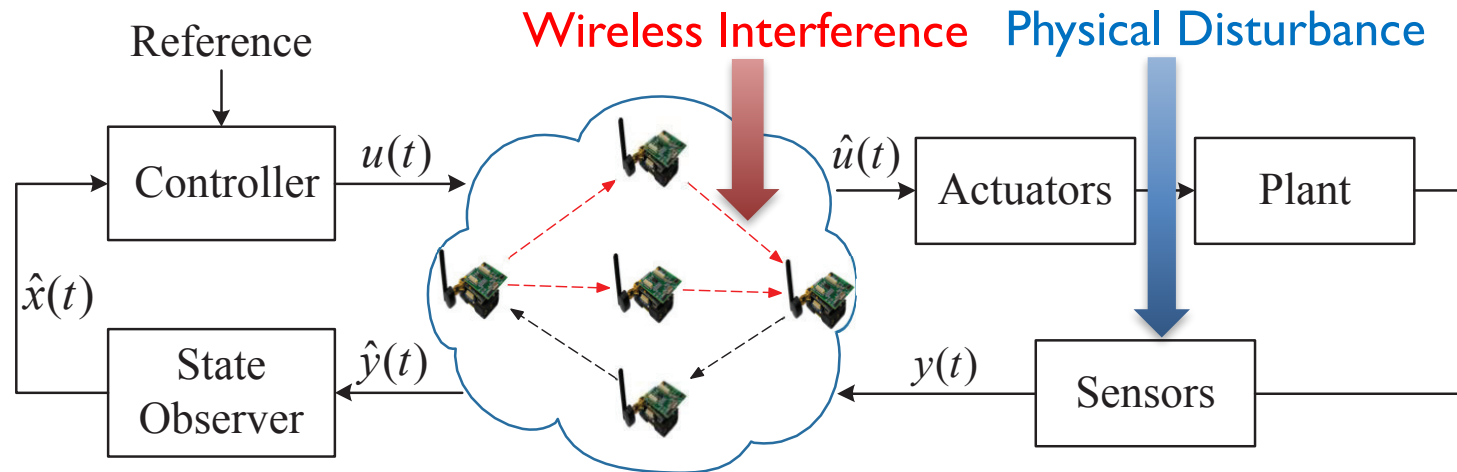
[Forbes]

Dependable Wireless Control System



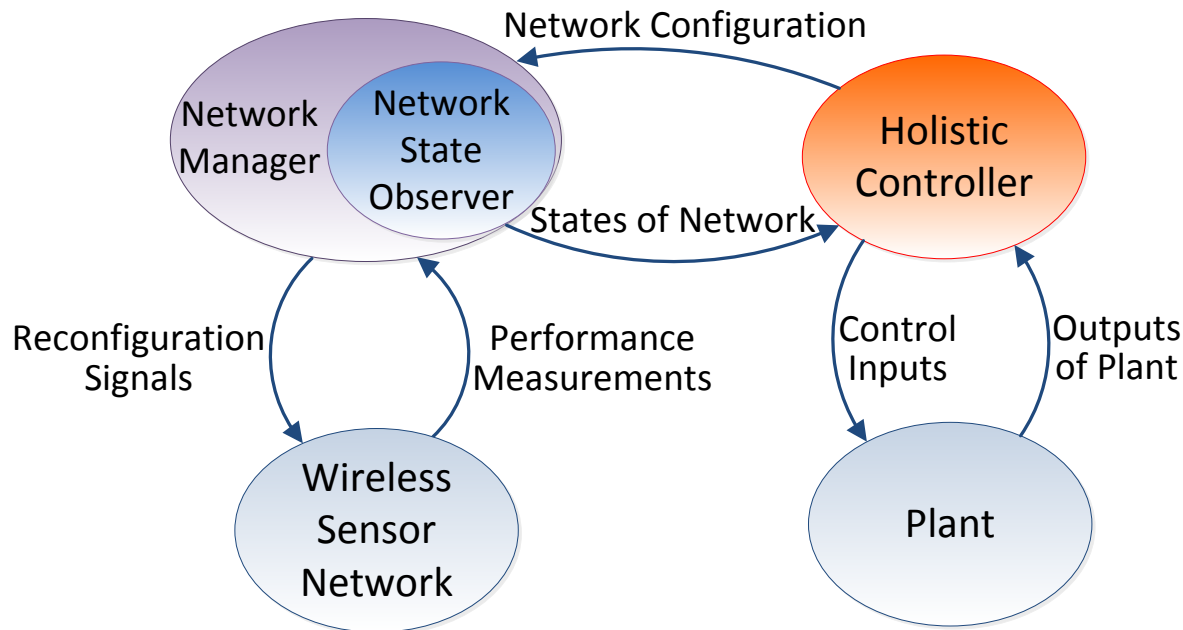
Most of today's industrial wireless networks are for monitoring

- Dependable wireless control requires
- Control performance
 - Resiliency
 - Energy efficiency



Holistic Control

- Close the loop between control and network
- Holistic controller manages both the physical plant and network based on states of plants and the network



Ma, Y., Gunatilaka, D., Li, B., Gonzalez, H., & Lu, C. (2018). Holistic cyber-physical management for dependable wireless control systems. *ACM Transactions on Cyber-Physical Systems*, 3(1), 3.

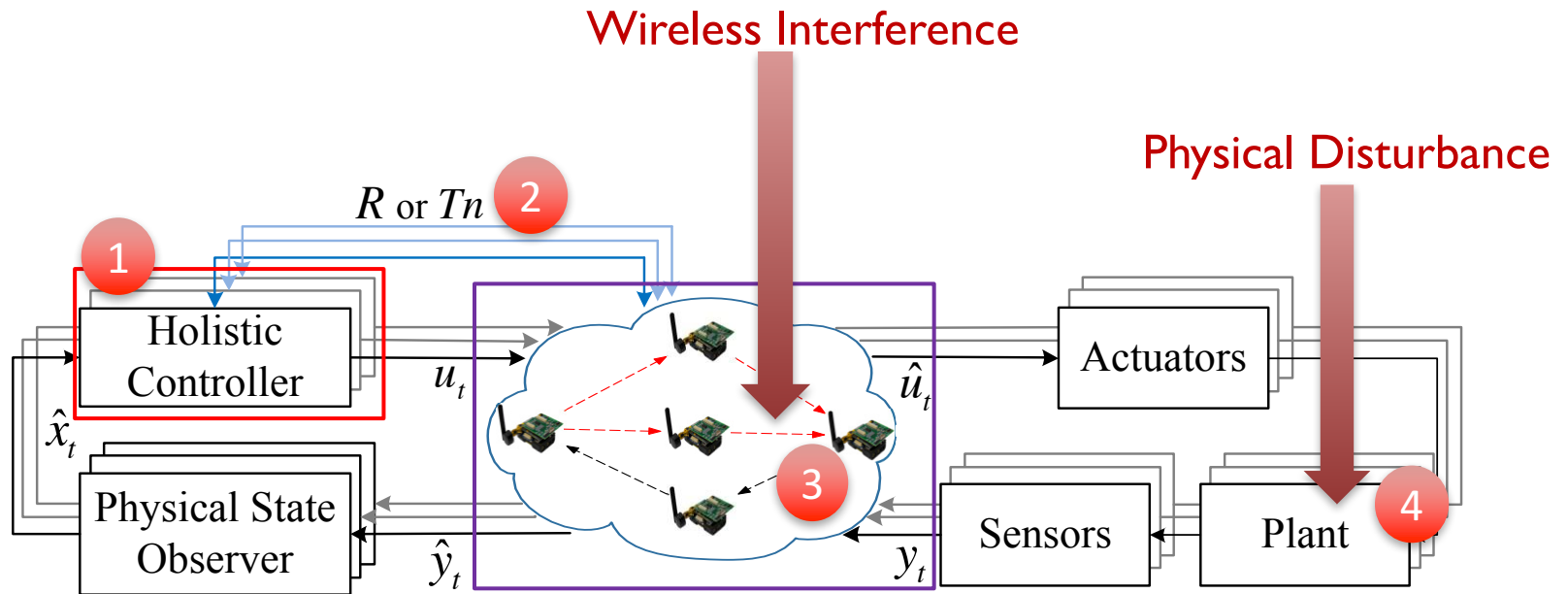
Motivation

- Traditional periodic control
 - ❑ Low rate → Low resiliency to interference
 - ❑ High rate → Unnecessary energy cost
 - **Efficient** rate-adaptation/event-triggered control
- Time-slotted multi-hop mesh WSAN
 - ❑ Lack of mechanism tailored for efficient control strategies
 - ❑ Run-time reconfiguration is challenging
- Simulation tools are of vital importance for wireless control
 - ❑ Real WSAN dynamics are hard to simulate
 - ❑ Running real industrial physical plant is extremely challenging

Contributions

- Holistic control with efficient control strategies
 - ❑ Rate adaptation
 - ❑ Self-triggered control
- WSAN reconfiguration mechanisms
 - ❑ Support run-time adaptation for efficient holistic control
 - ❑ Target multi-hop mesh network
- Real-time network-in-the-loop simulator
 - ❑ Real WSAN testbed
 - ❑ Simulated physical plants and controllers
- Compare rate adaptation and self-triggered control

Efficient Holistic Control Framework

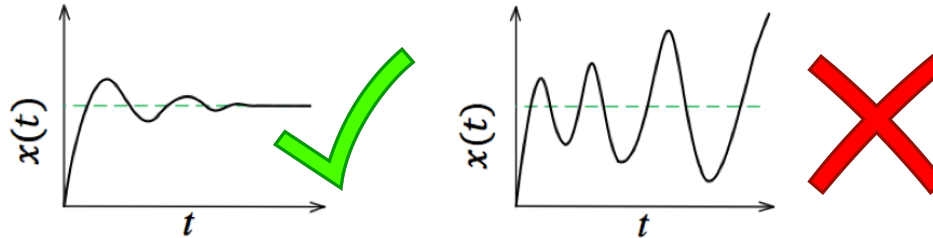


- Control performance monitoring
- Efficient control strategy → Rate/Inter-transmission time

- Network reconfiguration mechanism

Control Performance Monitoring

➤ Stability



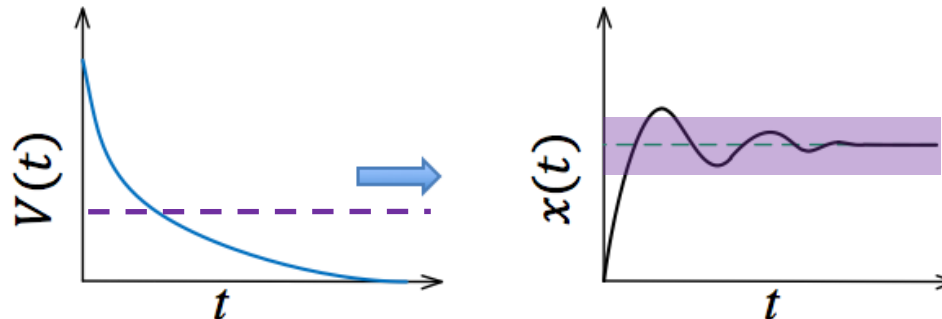
➤ State error

❑ $\|x(t) - \text{reference state}\|$

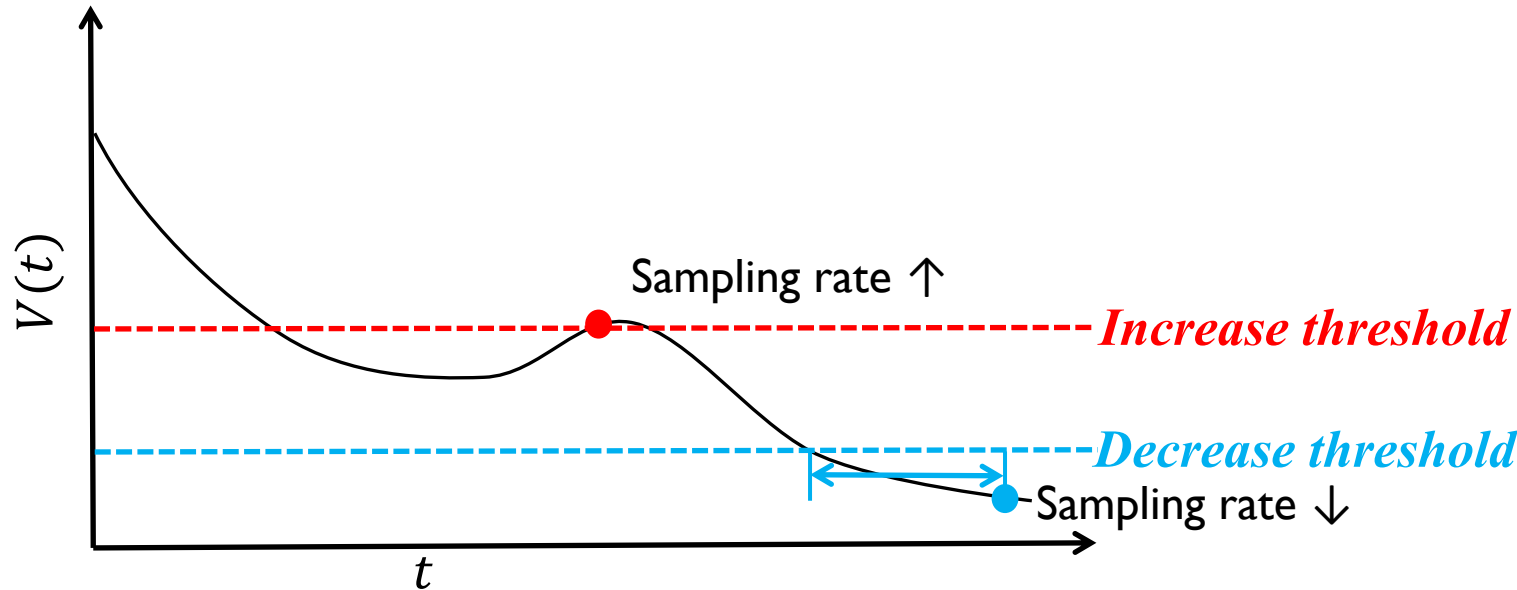
➤ Control performance index: Lyapunov function $V(x(t))$

❑ $V(x(t))$ keeps decreasing \rightarrow System is stable

❑ Value of $V(x(t)) \rightarrow$ upper bound of physical state error



Rate Adaptation



➤ Simplified of the rate adaptation algorithm

If *Increase threshold*

→ *Sampling rate* \uparrow

If *Decrease threshold for a time interval*

→ *Sampling rate* \downarrow

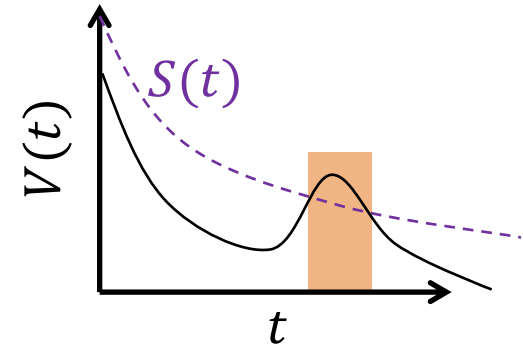
Self-triggered Control

➤ Event trigger rule

- ❑ Stability index is specified by: $S(t)$

$$S(x_t) = V(x_{t_{k-1}})e^{-\gamma V(x_{t_{k-1}})\delta(t-t_{k-1})}$$

- ❑ Ideal Lyapunov function $V(t) \leq S(t)$
- ❑ Trigger when $V(t) \geq S(t)$



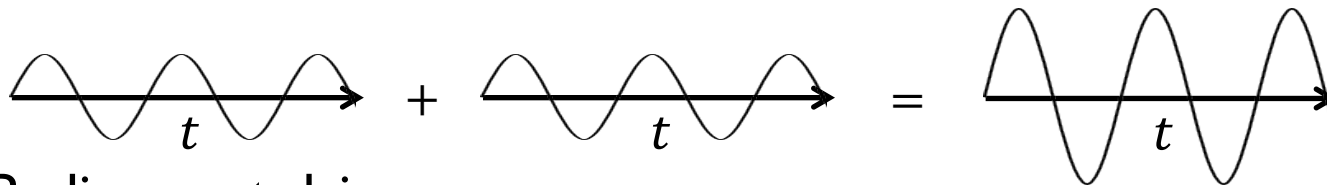
➤ Self triggered control

- ❑ Predict when the trigger condition will be violated based on model

Low-power Wireless Bus (LWB)

➤ Glossy flooding

- ❑ One to many
- ❑ Constructive interference



- ❑ Radio event driven
- ❑ Fast (propagation delay < 10 ms in 100-node mesh network)

➤ Low power wireless bus (LWB) network protocol

- ❑ Maps all communication on fast Glossy floods → many to many

Ferrari, F., Zimmerling, M., Thiele, L., & Saukh, O. Efficient network flooding and time synchronization with glossy. *In IPSN*, 2011.

Ferrari, F., Zimmerling, M., Mottola, L., & Thiele, L. Low-power wireless bus. *In Sensys*, 2012.

Low-power Wireless Bus (LWB)

➤ Advantages of LWB

- Fast
- Topology independent
- Suitable for network-wide adaptation

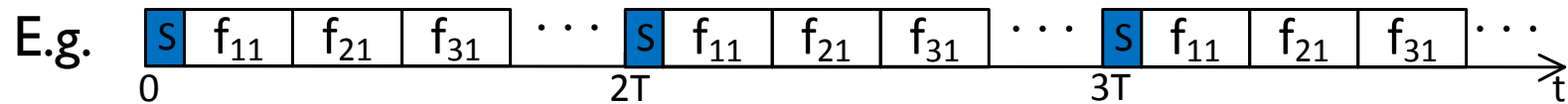
➤ Challenges of network design

- Support reconfiguration of whole communication schedules
- Recover from data loss during adaptation

Rate Adaptation: Network Design

➤ Network reconfiguration mechanism

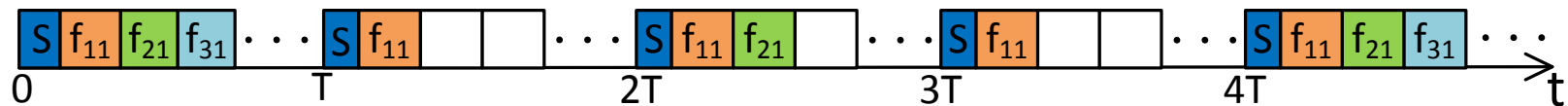
- ❑ All nodes store global static schedule (**max rate**)



- ❑ Holistic controllers piggyback the updated rate with actuation packet, and flood them in their assigned slot

$$f_{11}: \frac{1}{T} \text{ Hz} \quad f_{12}: \frac{1}{2T} \text{ Hz} \quad f_{13}: \frac{1}{4T} \text{ Hz}$$

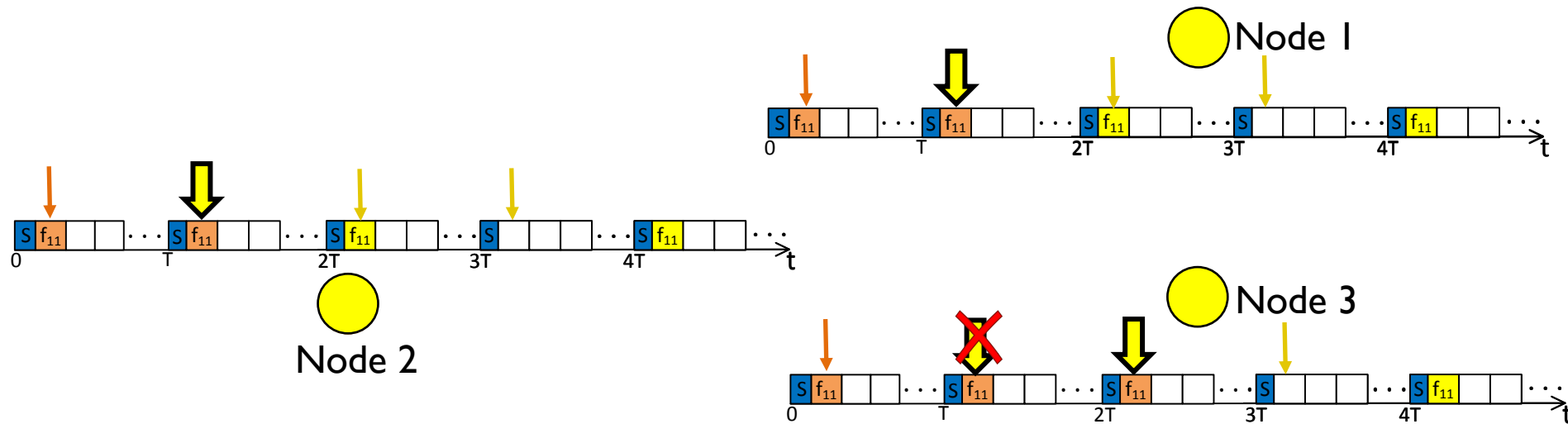
- ❑ Every node receives updated rates and calculates its schedule locally using **implicit scheduling** (e.g., based on rate monotonic scheduling)



- All nodes sleep at unassigned slots

Rate Adaptation: Packet Loss Recovery

If a node loses updated rate of loop i , it will continue to use latest rate it receives until another updated rate of loop i is received

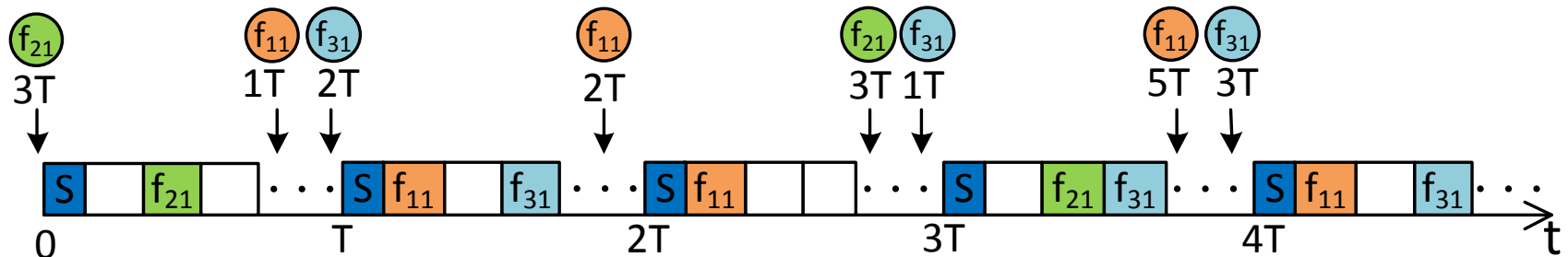


- ❑ The node recovers faster from packet loss if candidate rates share more common slots
- Candidate rate selection
 - ❑ Candidate rates should be harmonic

Self-triggered Control: Network Design

➤ Network reconfiguration mechanism

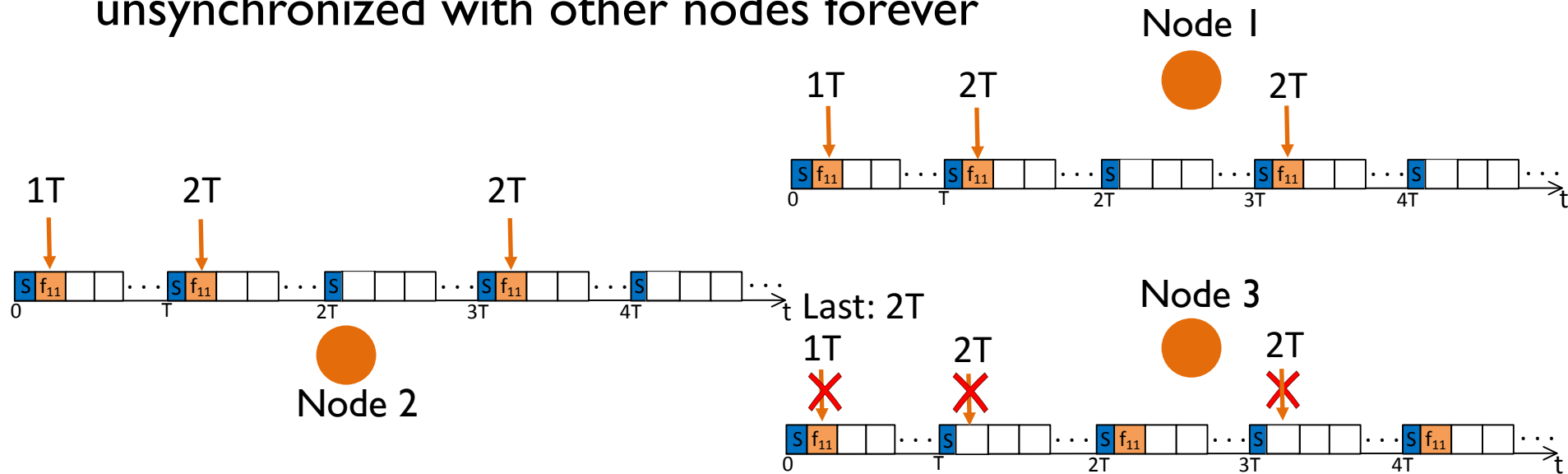
- ❑ All nodes store global static schedule (max rate)
- ❑ Holistic controllers piggyback the predicted time till the next transmission with actuation packet, and flood them in their assigned slots
- ❑ Every node sets up timers for each flow



- All nodes sleep at inactive slots

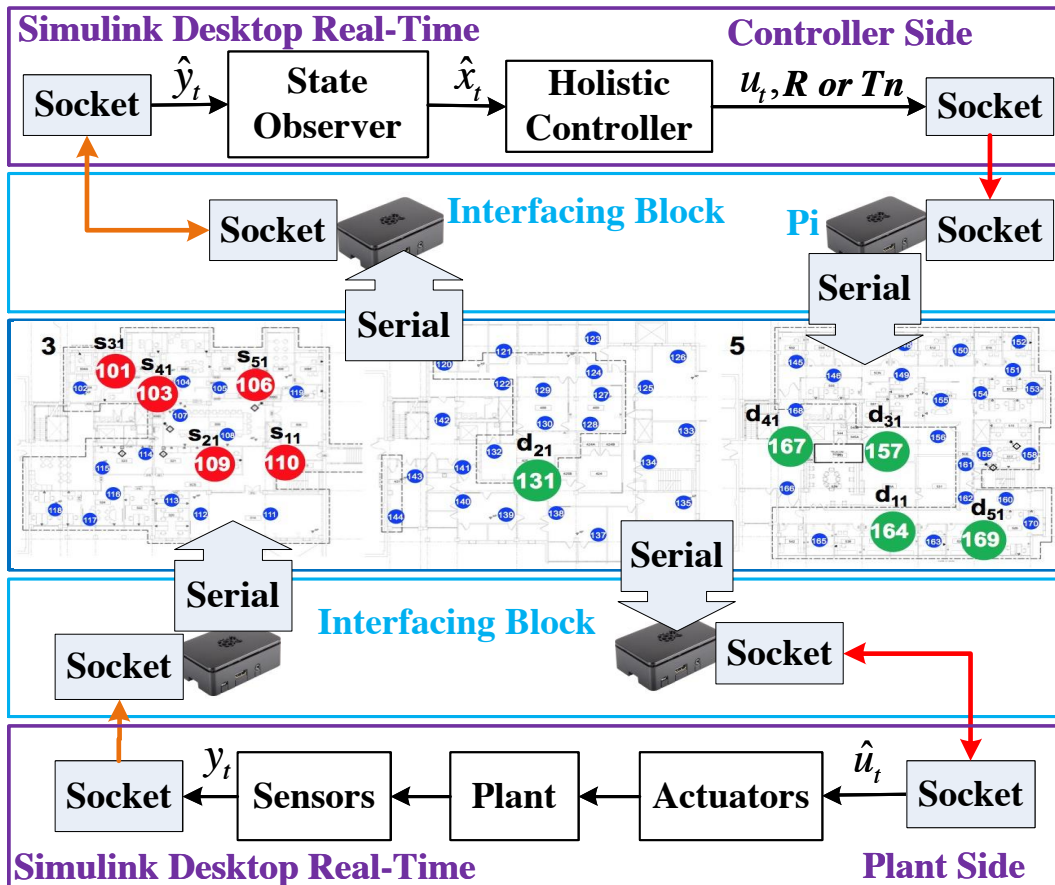
Self-Triggered Control: Packet Loss Recovery

Problem: If a node fails to receive the predicted time till the next transmission, it may wake up at the wrong time and become unsynchronized with other nodes forever



Solution: If a node loses inter-transmission time of a loop, it should re-awake at the **highest rate** until another actuation packet of this loop is received

WCPS-RT for Hybrid Simulation



Wireless Cyber-Physical Simulator (WCPS)

- MATLAB/Simulink
- TOSSIM
- wcps.cse.wustl.edu

Li, B., et. al, realistic case studies of wireless structural control. In ICCPS, 2013

WCPS-RT: Hybrid Simulations

- real wireless networks + simulated physical plants
- capture wireless dynamics that are hard to simulate accurately
- leverage simulation support for controllers and plants.

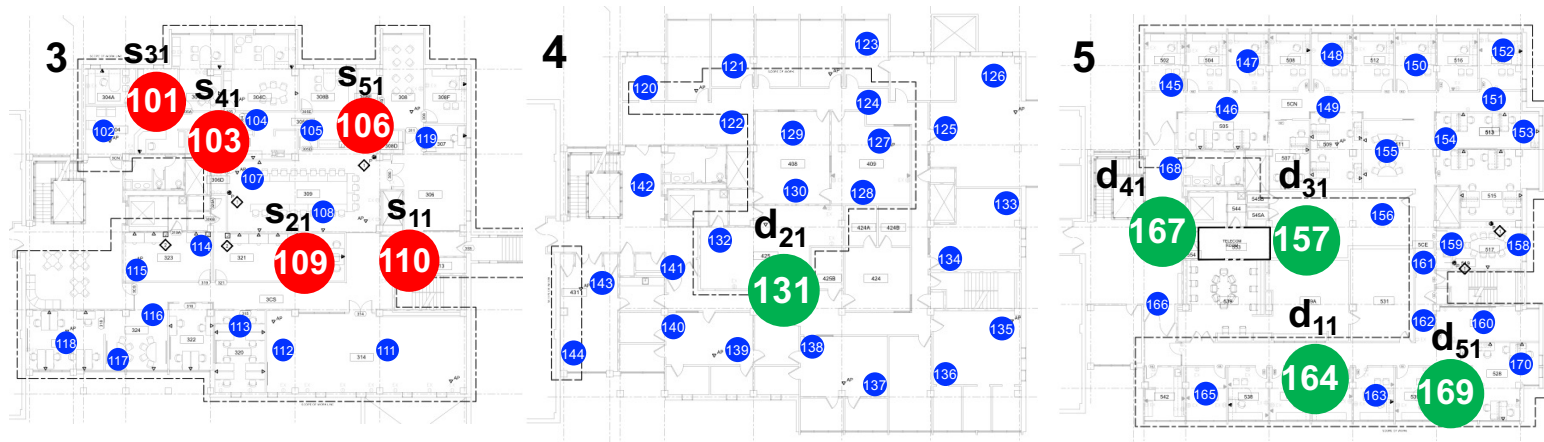
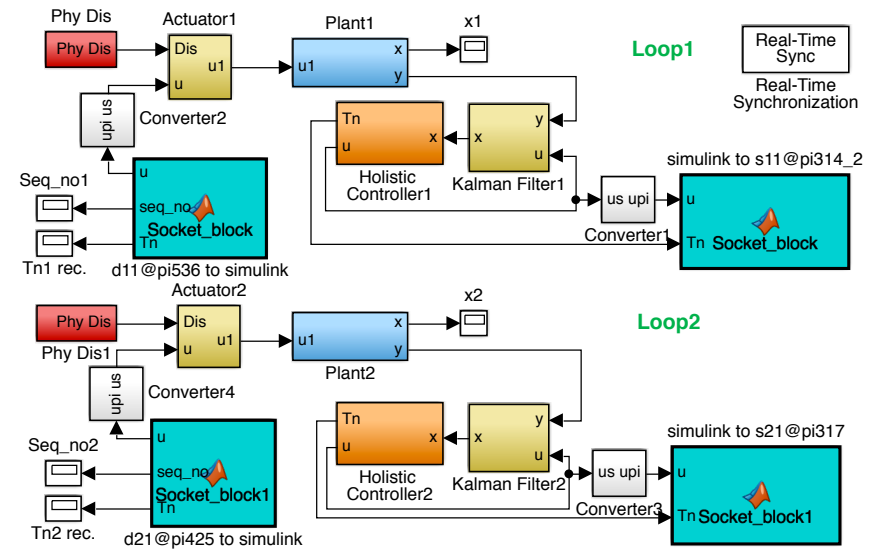
Experimental Settings

➤ Physical plant and controller

- ❑ Up to five 4-state load positioning plants

➤ 3- floor WSAN@WUSTL

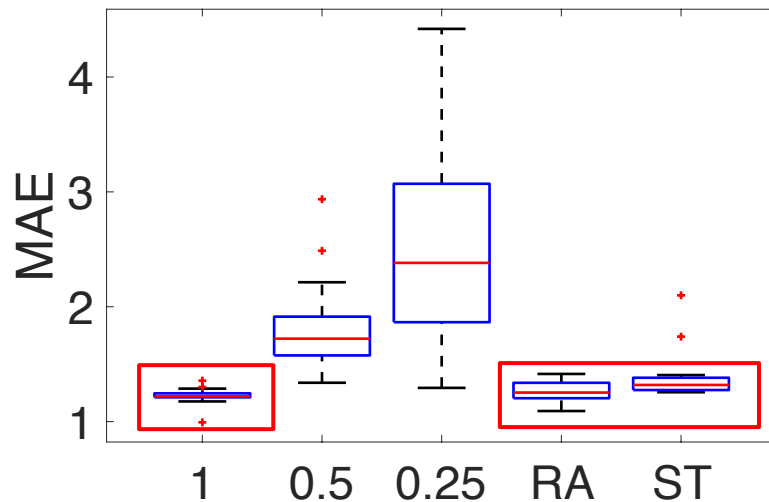
- ❑ 70 TelosB motes



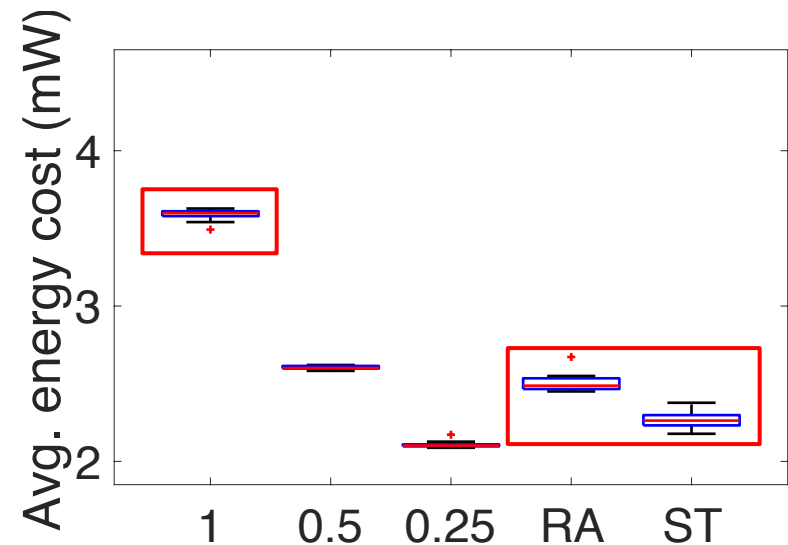
Normal Condition

Control performance metric:

$$MAE = \frac{1}{n+1} \sum_{k=0}^n |x(k) - x_{ref}(k)|,$$



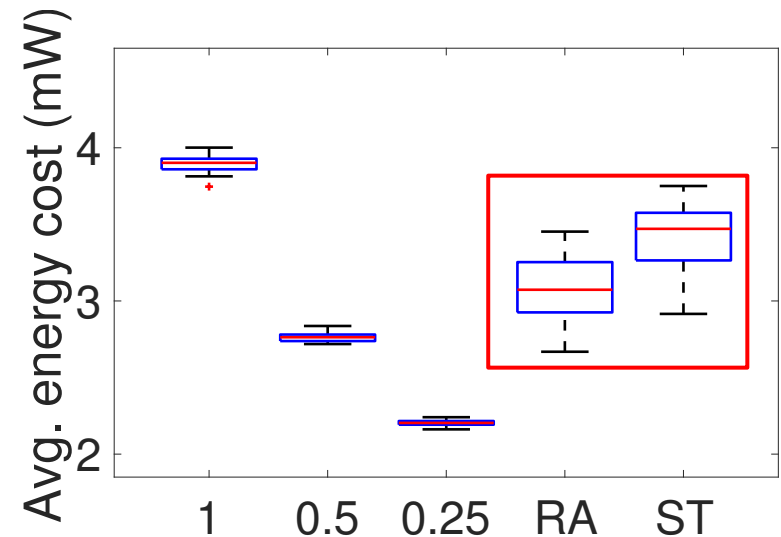
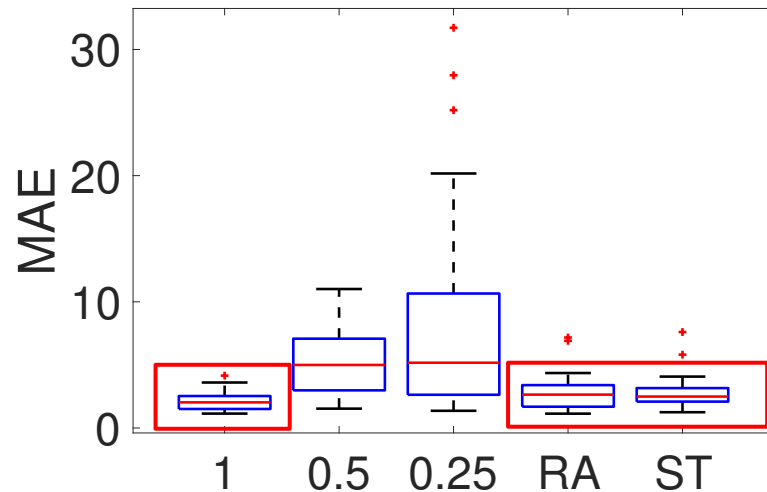
- RA: Rate Adaptation
- ST: Self-Triggered control



- RA and ST have **similar control performance** to fixed 1 Hz sampling
- while incurring over **40% fewer energy consumption** in the network!
- ST is more aggressive in energy saving than RA

Under Wireless Interference

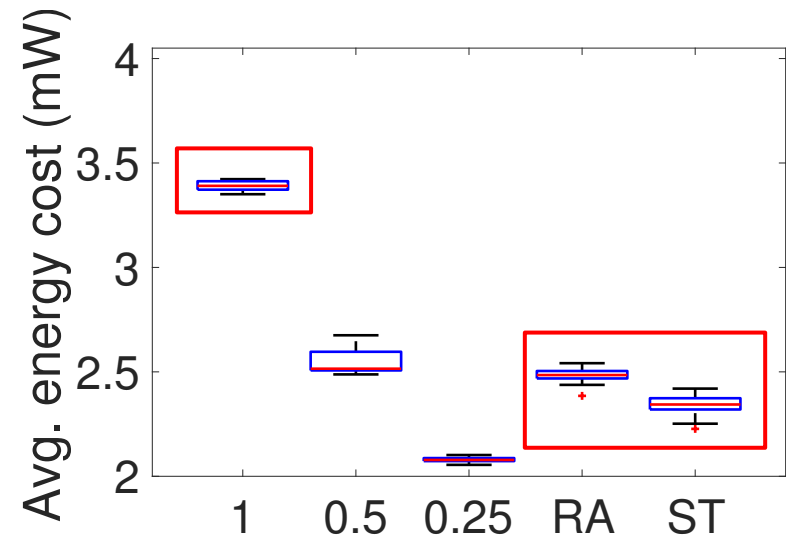
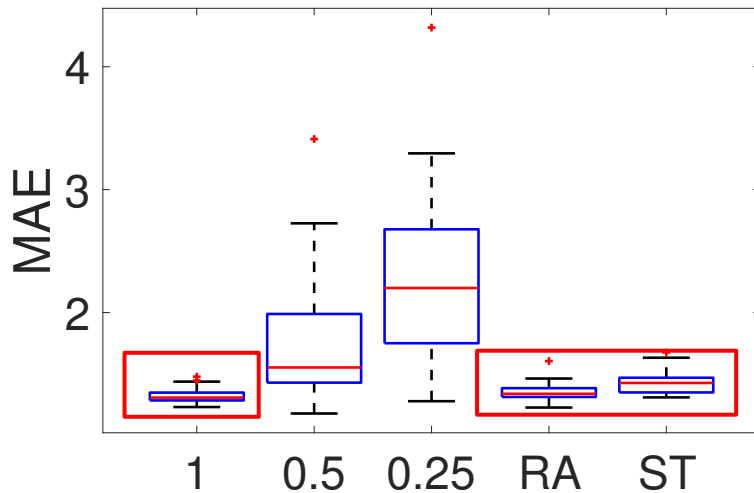
Interference generated by WiFi



- RA and ST have **similar control performance** to fixed 1 Hz sampling
- Higher energy cost due to recovery, but still lower than 1 Hz sampling
- ST consumes more energy than RA, due to packet loss recovery

Under Physical Disturbance

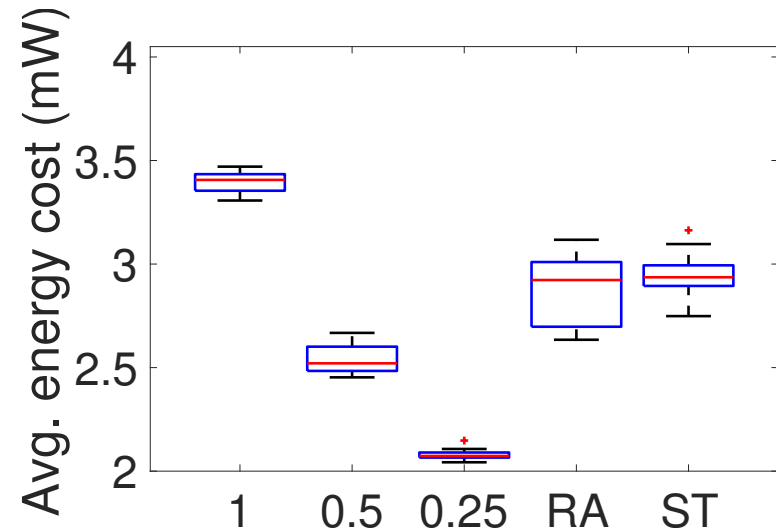
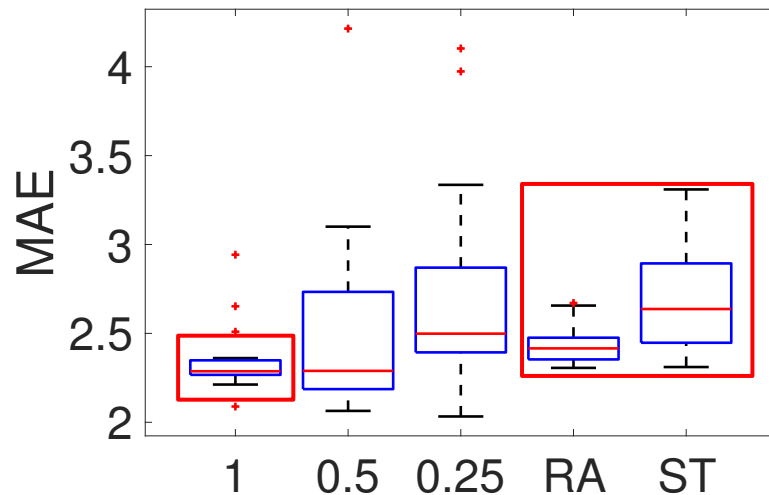
- Disturbance: constant bias of actuators
- Performance over the entire experiments



- RA and ST have **similar control performance** to fixed 1 Hz sampling
- Energy consumption reduction of more than 30%

Under Physical Disturbance

- During the disturbance (120s – 180s)



- ST performs worse than RA under disturbance
- Longer inter-transmission interval → slow responsive to disturbance

Conclusion

- Holistic control enhances efficiency and resiliency of wireless control systems

- Incorporate two efficient holistic control designs
 - ❑ Rate Adaptation (RA)
 - ❑ Self-Triggered control (ST)

- Novel network reconfiguration mechanisms based on LWB

- Hybrid wireless control experiments based on WCPS-RT
 - ❑ RA and ST offer advantages in control performance and efficiency
 - ❑ ST is less efficient than RA under network interference due to loss recovery
 - ❑ ST can be less responsive to physical disturbances due to predicted transmission time